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The Gurevich theorem on invariant tensors: Elementary proof

Demeter Krupka Lepage Research Institute 17 November St., 081 16 Presov Slovakia demeter.krupka@lepageri.eu

Abstract A simple proof of a fundamental theorem of the classical algebraic invariant theory, characterizing the structure of invariant tensors (tensors with constant components), the *Gurevich theorem*, is given. The proof is based on the trace decomposition theorem.

Keywords Tensor, Invariant, Trace, Permutation group **Mathematics subject classification (2010)** 15A72, 20G05, 53A45, 53A55

1 Introduction

The goal of this note is to give an elementary proof of a fundamental result of the classical algebraic invariant theory, the *Gurevich theorem* on the structure of invariant tensors (tensors with constant components).

The classification problem for invariant tensors was studied by several authors, and different approaches and proofs were presented (cf. Gurevich [2], Theorem 16.2, Sec. 16.5). The problem was also considered as a part of the theory of differential invariants and natural operations in differential geometry (Krupka and Janyska [6], Sec. 4.1, Kolar, Michor and Slovak [3], Sec. 24.3), with proofs based essentially on the original Gurevich approach. The proof given in this paper is based on application of the trace decomposition theory of tensors over real, finite-dimensional vector spaces (Krupka [4], [5]) to invariant tensor equations, found by Gurevich. We solve these equations by simple immediate analysis; the method avoids, in particular, the Gurevich's approach regarding linear dependences appearing in the equations for higher valency tensors.

For basic notions and terminology related to invariants, matrix groups and permutation groups we refer to H. Weyl [7] and Alperin and Bell [1].

In Section 2 we first recall the *trace decomposition theorem* for (r,r)-tensors, then we state its second version, the *complete trace decomposition theorem*. For proofs and further comments we refer to Krupka [4], [5]. Section 3 contains the theory of tensors on the vector space \mathbb{R}^n , *invariant* under the tensor action of the general linear group. The *Gurevich* theorem, stating that invariant tensors are essentially determined by real-valued functions on the permutation group of tensor indices, is proved as a corollary to the complete trace decomposition theorem.

In this paper $T_s^r \mathbf{R}^n$ is the vector space of tensors of type (r,s) on the vector space \mathbf{R}^n ((r,s)-tensors). For short, we usually express tensors $U \in T_s^r \mathbf{R}^n$ in terms of components in the *canonical basis* of \mathbf{R}^n ; we simply write $U = U^{k_i k_2 \dots k_r}_{l_i l_2 \dots l_s}$. $GL_n(\mathbf{R})$ is the general linear group, with elements invertible matrices $A = A_j^i$ of dimension *n*; the *inverse* A^{-1} is in components denoted by $A^{-1} = \tilde{A}_j^i$. Thus, $A_j^i \tilde{A}_k^j = \delta_k^i$, where δ_k^i is the *Kronecker symbol*. The *permutation group* of the set of *r* numbers $\{1, 2, \dots, r\}$ is denoted by S_r . Standard summation convention over repeated indices is used unless otherwise stated.

2 Trace decomposition of tensor spaces

Recall that a tensor is said to be *traceless*, if all its traces vanish. A *Kronecker tupe tensor*, or just a *Kronecker tensor*, is any tensor, generated by the Kronecker δ -tensor $\delta = \delta_i^i$.

Lemma 1 Every tensor $U \in T_r^r \mathbf{R}^n$, $U = U^{i_1 i_2 \dots i_r}_{j_1 j_2 \dots j_r}$, is expressible in the form

$$U^{i_{1}i_{2}...i_{r}}_{j_{1}j_{2}...j_{r}} = W^{i_{1}i_{2}...i_{r}}_{j_{1}j_{2}...j_{r}} + \delta^{i_{1}}_{j_{2}} V^{i_{2}i_{3}...i_{r}}_{j_{2}j_{3}...j_{r}} + \dots + \delta^{i_{1}}_{j_{r}} V^{i_{2}i_{3}...i_{r}}_{j_{r}}_{j_{2}j_{3}...j_{r}} + \delta^{i_{1}}_{j_{2}} V^{i_{2}i_{3}...i_{r}}_{j_{1}j_{3}...j_{r}} + \dots + \delta^{i_{1}}_{j_{r}} V^{i_{2}i_{3}...i_{r}}_{j_{r}}_{j_{1}j_{2}...j_{r-1}} + \delta^{i_{2}}_{j_{1}} V^{i_{1}i_{3}...i_{r}}_{j_{2}j_{3}...j_{r}} + \delta^{i_{2}}_{j_{2}} V^{i_{1}i_{3}...i_{r}}_{j_{1}j_{3}...j_{r}} + \dots + \delta^{i_{2}}_{j_{r}} V^{i_{1}i_{3}...i_{r}}_{j_{r}}_{j_{1}j_{2}...j_{r-1}} + \dots + \delta^{i_{r}}_{j_{1}} V^{i_{1}i_{2}...i_{r-1}}_{j_{2}j_{3}...j_{r}} + \delta^{i_{r}}_{j_{2}} V^{i_{1}i_{2}...i_{r-1}}_{j_{1}j_{3}...j_{r}} + \dots + \delta^{i_{r}}_{j_{r}} V^{i_{1}i_{2}...i_{r-1}}_{j_{r}}_{j_{1}j_{2}...j_{r-1}}$$

where $W = W^{i_1i_2...i_r}_{j_1j_2...j_r}$ is a uniquely defined traceless tensor, and for every p and q such that $\prod_{i=1}^{r} p_i q \leq r$, $p_i^p V = p_i^p V^{i_1i_2...i_{r-1}}_{j_1j_2...j_{r-1}}$ is a tensor, belonging to the tensor space $T_{r-1}^{r-1} \mathbf{R}^n$.

The *trace decomposition formula* (1) can be viewed as a system of linear equations for the components $W^{i_1i_2...i_r}_{l_1l_2...l_r}$ and ${}^p_q V^{i_1i_2...i_{r-1}}_{j_1j_2...j_{r-1}}$ provided $U^{i_1i_2...i_r}_{j_1j_2...j_r}$ is given. From the uniqueness of the *traceless part* $W^{i_1i_2...i_r}_{j_1j_2...j_r}$ it follows that also the complementary *Kronecker part* is unique. In general, this fact does not imply the uniqueness of the tensors ${}^p_q V^{i_1i_2...i_{r-1}}_{j_1j_2...j_{r-1}}$. However, if $2r \le n+1$, these tensors are also unique.

ever, if $2r \le n+1$, these tensors are also unique. Clearly, tensors ${}^{p}_{q}V^{i_{l_{2}...l_{r-1}}}$ can also be decomposed by the trace decomposition formula; repeating this procedure *r* times, we can derive from formula (1) another expression for (r,r)-tensors on \mathbf{R}^{n} .

Let *p* be a positive integer. A tensor $U \in T_r^r \mathbf{R}^n$, $U = U^{i_1 i_2 \dots i_r}_{j_1 j_2 \dots j_r}$, is said to be $\delta^{(p)}$ -generated, if it admits an expression

$$U^{i_1i_2\ldots i_r}_{j_1j_2\ldots j_r} = \sum_{\kappa,\lambda\in S_r} \delta^{i_{\lambda(1)}}_{j_{\kappa(1)}} \delta^{i_{\lambda(2)}}_{j_{\kappa(2)}} \ldots \delta^{i_{\lambda(p)}\ \lambda(1),\lambda(2),\ldots,\lambda(p)}_{j_{\kappa(p)}\ \kappa(1),\kappa(2),\ldots,\kappa(p)} V^{i_{\lambda(p+1)}i_{\lambda(p+2)}\ldots i_{\lambda(r)}}_{j_{\kappa(p+1)}j_{\kappa(p+2)}\ldots j_{\kappa(r)}}$$

for some tensors $\lambda_{\kappa(1),\kappa(2),\dots,\kappa(p)}^{\lambda(1),\lambda(2),\dots,\lambda(p)} V \in T_{r-p}^{r-p} \mathbf{R}^n$ (indexed on the left),

$${}^{\lambda(1),\lambda(2),\dots,\lambda(p)}_{\kappa(1),\kappa(2),\dots,\kappa(p)} V = {}^{\lambda(1),\lambda(2),\dots,\lambda(p)}_{\kappa(1),\kappa(2),\dots,\kappa(p)} V^{i_1i_2\dots i_{r-p}}_{j_1j_2\dots j_{r-p}}.$$

If in addition the tensors $\lambda_{\kappa(1),\kappa(2),\dots,\kappa(p)}^{\lambda(1),\lambda(2),\dots,\lambda(p)}V$ are *traceless*, then U is said to be *primitive*.

Lemma 2 Every tensor $U \in T_r^r \mathbf{R}^n$, $U = U^{i_1 i_2 \dots i_r}_{j_1 j_2 \dots j_r}$, is expressible in the form

(2)
$$U = {}^{0}U + {}^{1}U + {}^{2}U + \ldots + {}^{r}U,$$

where ⁰U is a traceless tensor, and for every p = 1, 2, ..., r, ^pU is a $\delta^{(p)}$ -generated primitive tensor. Decomposition (2) is unique.

Tensors ${}^{0}U, {}^{1}U, {}^{2}U, \dots, {}^{r}U$ are called *primitive parts* of U.

3 Invariant tensors

Recall that the tensor space $T_s^r \mathbf{R}^n$ is endowed with the canonical left tensor action $GL_n(\mathbf{R}) \times T_s^r \mathbf{R}^n \ni (A,U) \to A \cdot U \in T_s^r \mathbf{R}^n$ of the general linear group $GL_n(\mathbf{R})$. Expressing tensors U and $A \cdot U$ as $U = U^{i_1 i_2 \dots i_r}_{j_1 j_2 \dots j_s}$ and $A \cdot U = \overline{U}^{i_1 i_2 \dots i_r}_{j_1 j_2 \dots j_s}$, equations of the tensor action are

(3)
$$\overline{U}^{k_1k_2...k_r}_{l_1l_2...l_s} = A^{k_1}_{i_1}A^{k_2}_{i_2}...A^{k_r}_{i_r}\widetilde{A}^{j_1}_{l_1}\widetilde{A}^{j_2}_{l_2}...\widetilde{A}^{j_s}_{l_s}U^{l_1l_2...l_r}_{j_1j_2...j_s}.$$

A tensor $U \in T_s^r \mathbf{R}^n$ is said to be *invariant*, if $A \cdot U = U$ for all elements $A \in GL_n(\mathbf{R})$, that is,

(4)
$$U^{k_1k_2...k_r}_{l_1l_2...l_s} = A^{k_1}_{i_1}A^{k_2}_{i_2}...A^{k_r}_{i_r}\tilde{A}^{j_1}_{l_1}\tilde{A}^{j_2}_{l_2}...\tilde{A}^{j_s}_{l_s}U^{i_1i_2...i_r}_{j_1j_2...j_s}.$$

Invariant tensors constitute a vector subspace of the tensor space $T_s^r \mathbf{R}^n$.

The classification problem for (r, s)-tensors such that $r \neq s$, has only trivial solution.

Lemma 1 If $r \neq s$, then a tensor $U \in T_s^r \mathbf{R}^n$ is invariant if and only if U = 0.

Proof Suppose for instance that r > s. If A is a matrix with components $A_i^k = c\delta_i^k$, where $c \neq 0$, then the components of the inverse matrix A^{-1} are $\tilde{A}_i^k = (1/c)\delta_i^k$. In this case equations (3) reduce to

$$U^{k_1k_2...k_r}_{l_1l_2...l_s} = c^{r-s} U^{k_1k_2...k_r}_{l_1l_2...l_s}$$

with arbitrary c. But $r - s \neq 0$ hence $U^{k_1 k_2 \dots k_r}_{l_1 l_2 \dots l_s} = 0$.

For r = s invariance condition (4) reads

(5)
$$A_{i_1}^{k_1} A_{i_2}^{k_2} \dots A_{i_r}^{k_r} \tilde{A}_{l_1}^{j_1} \tilde{A}_{l_2}^{j_2} \dots \tilde{A}_{l_r}^{j_r} U^{i_1 j_2 \dots i_r}{}_{j_1 j_2 \dots j_r} = U^{k_1 k_2 \dots k_r}{}_{l_1 l_2 \dots l_r}$$

or, equivalently,

(6)
$$A_{l_1}^{k_1}A_{l_2}^{k_2}\dots A_{l_r}^{k_r}U^{l_1l_2\dots l_r}_{j_1j_2\dots j_r} = A_{j_1}^{l_1}A_{j_2}^{l_2}\dots A_{j_r}^{l_r}U^{k_1k_2\dots k_r}_{l_1l_2\dots l_r}$$

Lemma 2 Let $U \in T_r^r \mathbb{R}^n$, $U = U^{k_l k_2 \dots k_r}_{l_l l_2 \dots l_r}$. The following two conditions are equivalent:

- (a) *U* is an invariant tensor.
- (b) The components $U^{i_1i_2...i_r}_{j_1j_2...j_r}$ satisfy

(7)
$$\sum_{\tau \in S_r} \delta_{j_1}^{i_{\tau(1)}} \delta_{j_2}^{i_{\tau(2)}} \dots \delta_{j_r}^{i_{\tau(r)}} U^{k_l k_2 \dots k_r}_{l_{\tau(1)} l_{\tau(2)} \dots l_{\tau(r)}} \\ = \sum_{\tau \in S_r} \delta_{l_{\tau(1)}}^{k_1} \delta_{l_{\tau(2)}}^{k_2} \dots \delta_{l_{\tau(r)}}^{k_r} U^{i_{\tau(1)} i_{\tau(2)} \dots i_{\tau(r)}}_{j_1 j_2 \dots j_r}.$$

Proof 1. Suppose that invariance condition (a), that is, equation (6), is satisfied. Consider the difference

$$A_{l_1}^{k_1}A_{l_2}^{k_2}\ldots A_{l_r}^{k_r}U^{l_ll_2\ldots l_r}{}_{j_1j_2\ldots j_r}-A_{j_1}^{l_1}A_{j_2}^{l_2}\ldots A_{j_r}^{l_r}U^{k_1k_2\ldots k_r}{}_{l_ll_2\ldots l_r}.$$

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In this expression A_j^i enters as an arbitrary element of the group $GL_n(\mathbf{R})$, which can be considered as an open set in a vector space $\mathbf{R}^n \times (\mathbf{R}^n)^*$ of all square matrices $\theta \in \mathbf{R}^n \times (\mathbf{R}^n)^*$, $\theta = \theta_j^i$. But $U^{k_1k_2...k_r}_{l_1l_2...l_r}$ defines a mapping of the vector space $\mathbf{R}^n \times (\mathbf{R}^n)^*$ into the tensor space $T_r^r \mathbf{R}^n$ by the equations

$$V^{k_{1}k_{2}...k_{r}}_{p_{1}p_{2}...p_{r}} = \theta^{i_{1}}_{p_{1}}\theta^{i_{2}}_{p_{2}}...\theta^{i_{r}}_{p_{r}}U^{k_{1}k_{2}...k_{r}}_{i_{1}i_{2}..i_{r}} - \theta^{k_{1}}_{i_{1}}\theta^{k_{2}}_{i_{2}}...\theta^{k_{r}}_{i_{r}}U^{i_{1}i_{2}..i_{r}}_{p_{1}p_{2}...p_{r}}.$$

Writing $V_{p_1p_2...p_r}^{k_1k_2...k_r}$ in terms of coefficients, we have

$$\begin{aligned} V^{k_1k_2...k_r}_{p_1p_2...p_r} &= \theta^{\alpha_1}_{\beta_1}\theta^{\alpha_2}_{\beta_2}\dots\theta^{\alpha_r}_{\beta_r}(\delta^{i_1}_{\alpha_1}\delta^{i_2}_{\alpha_2}\dots\delta^{i_r}_{\alpha_r}\delta^{\beta_1}_{p_1}\delta^{\beta_2}_{p_2}\dots\delta^{\beta_r}_{p_r}U^{k_1k_2...k_r}_{i_li_2...i_r} \\ &-\delta^{k_1}_{\alpha_1}\delta^{k_2}_{\alpha_2}\dots\delta^{k_r}_{\alpha_r}\delta^{\beta_1}_{i_1}\delta^{\beta_2}_{i_2}\dots\delta^{\beta_r}_{p_r}U^{i_li_2...i_r}_{p_1p_2...p_r}) \\ &= \theta^{\alpha_1}_{\beta_1}\theta^{\alpha_2}_{\beta_2}\dots\theta^{\alpha_r}_{\beta_r}(\delta^{\beta_1}_{p_1}\delta^{\beta_2}_{p_2}\dots\delta^{\beta_r}_{p_r}U^{k_lk_2...k_r}_{\alpha_l\alpha_2...\alpha_r} \\ &-\delta^{k_1}_{\alpha_1}\delta^{k_2}_{\alpha_2}\dots\delta^{k_r}_{\alpha_r}U^{\beta_l\beta_2...\beta_r}_{p_1p_2...p_r}) \end{aligned}$$

or, with coefficients, symmetrized in the pairs of indices $\frac{\alpha_i}{\beta_i}$,

(8)

$$V^{k_{1}k_{2}...k_{r}}_{p_{1}p_{2}...p_{r}}$$

$$= \theta^{\alpha_{1}}_{\beta_{1}}\theta^{\alpha_{2}}_{\beta_{2}}...\theta^{\alpha_{r}}_{\beta_{r}}\sum_{\tau\in S_{r}} (\delta^{\beta_{\tau(1)}}_{p_{1}}\delta^{\beta_{\tau(2)}}_{p_{2}}...\delta^{\beta_{\tau(r)}}_{p_{r}}U^{k_{1}k_{2}...k_{r}}_{\alpha_{\tau(1)}\alpha_{\tau(2)}...\alpha_{\tau(r)}}$$

$$-\delta^{k_{1}}_{\alpha_{\tau(1)}}\delta^{k_{2}}_{\alpha_{\tau(2)}}...\delta^{k_{r}}_{\alpha_{\tau(r)}}U^{\beta_{\tau(1)}\beta_{\tau(2)}...\beta_{\tau(r)}}_{p_{1}p_{2}...p_{r}}).$$

Now if U is invariant, then $V^{k_1k_2...k_r}_{p_1p_2...p_r} = 0$ because $GL_n(\mathbf{R})$ is dense in $\mathbf{R}^n \times (\mathbf{R}^n)^*$ and the function $V^{k_1k_2...k_r}_{p_1p_2...p_r}$ is continuous; then, however, since θ^{α}_{β} are arbitrary,

(9)
$$\sum_{\tau \in S_r} (\delta_{p_1}^{\beta_{\tau(1)}} \delta_{p_2}^{\beta_{\tau(2)}} \dots \delta_{p_r}^{\beta_{\tau(r)}} U^{k_1 k_2 \dots k_r} \alpha_{\tau(1)} \alpha_{\tau(2)} \dots \alpha_{\tau(r)} \\ - \delta_{\alpha_{\tau(1)}}^{k_1} \delta_{\alpha_{\tau(2)}}^{k_2} \dots \delta_{\alpha_{\tau(r)}}^{k_r} U^{\beta_{\tau(1)} \beta_{\tau(2)} \dots \beta_{\tau(r)}} {}_{p_1 p_2 \dots p_r}) = 0.$$

Now formula (7) is obtained from (9) merely by changing the index notation $\beta \rightarrow i$, $p \rightarrow j$, and $\alpha \rightarrow l$.

2. Condition (b) implies (a) by means of (8).

Equivalent conditions (5), (6) and (7) are *equations of invariant tensors*. For every permutation $\sigma \in S_r$, set $\Delta_{\sigma} = \Delta_{\sigma}^{k_1 k_2 \dots k_r}{}_{\alpha_1 \alpha_2 \dots \alpha_r}$, where

$$\Delta_{\sigma}^{i_1i_2\ldots i_r}{}_{j_1j_2\ldots j_r} = \delta_{j_{\sigma(1)}}^{i_1} \delta_{j_{\sigma(2)}}^{i_2} \ldots \delta_{j_{\sigma(r)}}^{i_r}$$

 $\begin{array}{l} \Delta_{\sigma} \text{ can equivalently be defined by } \Delta_{\sigma}^{i_{lj_2...j_r}} = 1 \quad \text{if } i_p = j_{\sigma(p)} \text{ for all } \\ p = 1, 2, \ldots, n \text{ , and } \Delta_{\sigma}^{i_{lj_2...j_r}} = 0 \text{ otherwise.} \\ \text{ A notable property of the tensors } \Delta_{\sigma} \text{ is that their components define the } \\ stabilizers \text{ of the } r\text{-tuples of indices } i_1, i_2, \ldots, i_r \text{ with respect to the action of } \\ \text{the permutation group } S_r \text{. Equation of the stabilizer of } i_1, i_2, \ldots, i_r \text{ is } \end{array}$

$$\Delta_{\sigma}^{i_{1}i_{2}..i_{r}}_{i_{1}i_{2}..i_{r}} = \delta_{i_{\sigma(1)}}^{i_{1}}\delta_{i_{\sigma(2)}}^{i_{2}}...\delta_{i_{\sigma(r)}}^{i_{r}} = 1.$$

Lemma 3 (a) $\Delta_{\sigma} = \Delta_{\sigma}^{k_l k_2 \dots k_r}_{l_l l_2 \dots l_r}$ is an invariant tensor. (b) Any linear combination

(10)
$$U = \sum_{\sigma \in S_r} c_{\sigma} \Delta_{\sigma},$$

where $c_{\sigma} \in \mathbf{R}$, is an invariant tensor.

Proof (a) To prove Lemma 3, we use equation (7). Setting

$$U^{k_{l}k_{2}...k_{r}}_{l_{l}l_{2}..l_{r}} = \Delta^{k_{l}k_{2}...k_{r}}_{\sigma} = \delta^{k_{1}}_{l_{\sigma(1)}} \delta^{k_{2}}_{l_{\sigma(2)}} \dots \delta^{k_{r}}_{l_{\sigma(r)}},$$

we have $U^{k_l k_2 \dots k_r}_{l_{\tau(1)} l_{\tau(2)} \dots l_{\tau(r)}} = \delta^{k_1}_{l_{\sigma\tau(1)}} \delta^{k_2}_{l_{\sigma\tau(2)}} \dots \delta^{k_r}_{l_{\sigma\tau(r)}}$ and, with substitution $l_{\tau(p)} = j_p$,

$$U^{k_{1}k_{2}...k_{r}}_{l_{\tau(1)}l_{\tau(2)}...l_{\tau(r)}} = U^{k_{1}k_{2}...k_{r}}_{j_{1}j_{2}...j_{r}} = \delta^{k_{1}}_{j_{\sigma(1)}}\delta^{k_{2}}_{j_{\sigma(2)}}...\delta^{k_{r}}_{j_{\sigma(r)}}$$
$$= \delta^{k_{1}}_{l_{\tau\sigma(1)}}\delta^{k_{2}}_{l_{\tau\sigma(2)}}...\delta^{k_{r}}_{l_{\tau\sigma(r)}}.$$

Substituting these expressions into (7), we get for the left-hand side

$$\begin{split} &\sum_{\tau \in S_r} \delta_{j_1}^{i_{\tau(1)}} \delta_{j_2}^{i_{\tau(2)}} \dots \delta_{j_r}^{i_{\tau(r)}} U^{k_l k_2 \dots k_r}_{l_{\tau(1)} l_{\tau(2)} \dots l_{\tau(r)}} \\ &= \sum_{\tau \in S_r} \delta_{j_1}^{i_{\tau(1)}} \delta_{j_2}^{i_{\tau(2)}} \dots \delta_{j_r}^{i_{\tau(r)}} \delta_{l_{t\sigma(1)}}^{k_1} \delta_{l_{t\sigma(2)}}^{k_2} \dots \delta_{l_{t\sigma(r)}}^{k_r} \end{split}$$

The right-hand side is

$$\begin{split} &\sum_{\tau \in S_r} \delta_{l_{\tau(1)}}^{k_1} \delta_{l_{\tau(2)}}^{k_2} \dots \delta_{l_{\tau(r)}}^{k_r} U^{i_{\tau(1)}i_{\tau(2)} \dots i_{\tau(r)}}_{j_1 j_2 \dots j_r} \\ &= \sum_{\tau \in S_r} \delta_{l_{\tau(1)}}^{k_1} \delta_{l_{\tau(2)}}^{k_2} \dots \delta_{l_{\tau(r)}}^{k_r} \delta_{j_{\sigma(1)}}^{i_{\tau(\sigma(1)}} \delta_{j_{\sigma(2)}}^{i_{\tau(\sigma(2)}} \dots \delta_{j_{\sigma(r)}}^{i_{\tau(r)}}_{j_{\sigma(r)}} \\ &= \sum_{\tau \in S_r} \delta_{l_{\tau(1)}}^{k_1} \delta_{l_{\tau(2)}}^{k_2} \dots \delta_{l_{\tau(r)}}^{k_r} \delta_{j_1}^{i_{\tau(1)}} \delta_{j_2}^{i_{\tau(2)}} \dots \delta_{j_r}^{i_{\tau(r)}}, \end{split}$$

proving invariance. (b) Obvious.

Invariant tensors $\Delta_{(\sigma)}$ are called *elementary invariant tensors*.

Lemma 4 If $r \le n$, then every invariant tensor $U \in T_r^r \mathbf{R}^n$ has a unique expression (10).

Proof Consider the subsystem of (7) defined by $i_p = j_p = p$,

$$\begin{split} &\sum_{\tau \in S_r} \delta_1^{\tau(1)} \delta_2^{\tau(2)} \dots \delta_r^{\tau(r)} U^{k_1 k_2 \dots k_r}_{l_{\tau(1)} l_{\tau(2)} \dots l_{\tau(r)}} \\ &= \sum_{\tau \in S_r} \delta_{l_{\tau(1)}}^{k_1} \delta_{l_{\tau(2)}}^{k_2} \dots \delta_{l_{\tau(r)}}^{k_r} U^{\tau(1)\tau(2)\dots\tau(r)}_{12\dots r} \end{split}$$

But $\delta_1^{\tau(1)}\delta_2^{\tau(2)}...\delta_r^{\tau(r)} \neq 0$ if and only if $\tau(1) = 1, \tau(2) = 2,...,\tau(r) = r$; hence τ must be the identity permutation, and we have

$$U^{k_{1}k_{2}...k_{r}}_{l_{l}l_{2}...l_{r}} = \sum_{\tau \in S_{r}} \delta^{k_{1}}_{l_{\tau(1)}} \delta^{k_{2}}_{l_{\tau(2)}} \dots \delta^{k_{r}}_{l_{\tau(r)}} U^{\tau(1)\tau(2)...\tau(r)}_{12...r}.$$

Setting $c_{\tau} = U^{\tau(1)\tau(2)...\tau(r)}_{12...r}$ we get formula (10). To prove uniqueness of this decomposition, suppose that

$$\sum_{\sigma\in S_r} c_{\sigma} \Delta_{\sigma} = 0,$$

that is, in components,

$$\sum_{\tau\in S_r} c_\tau \delta_{l_{\tau(1)}}^{k_1} \delta_{l_{\tau(2)}}^{k_2} \dots \delta_{l_{\tau(r)}}^{k_r} = 0.$$

Then the component where $k_p = l_{\tau(p)} = p$ yields $c_{\tau} = 0$.

For $r \le n$, formula (10) clarifies the meaning of the coefficients:

$$\begin{split} U^{12...r}_{v(1)v(2)...v(r)} &= \sum_{\sigma \in S_r} c_{\sigma} \Delta_{\sigma}^{12...r}_{v(1)v(2)...v(r)} \\ &= \sum_{\sigma \in S_r} c_{\sigma} \delta_{v\sigma(1)}^1 \delta_{v\sigma(2)}^2 \dots \delta_{v\sigma(r)}^r = \sum_{\sigma \in S_r} c_{\sigma} \delta_{v(1)}^{\sigma^{-1}(1)} \delta_{v(2)}^{\sigma^{-1}(2)} \dots \delta_{v(r)}^{\sigma^{-1}(r)} \\ &= c_{v^{-1}}. \end{split}$$

We can also write $U^{v^{-1}(1)v^{-1}(2)\dots v^{-1}(r)}_{12\dots r} = c_{v^{-1}}$, thus, for every permutation τ ,

$$U^{\tau(1)\tau(2)\ldots\tau(r)}_{12\ldots r} = c_{\tau}.$$

Clearly, for any mutually different indices k_1, k_2, \dots, k_r ,

$$\begin{split} U^{k_{l}k_{2}...k_{r}}_{k_{\tau(1)}k_{\tau(2)}...k_{\tau(r)}} &= \sum_{\sigma \in S_{r}} c_{\sigma} \Delta_{\sigma}^{k_{l}k_{2}...k_{r}}_{k_{\tau(1)}k_{\tau(2)}...k_{\tau(r)}} \\ &= \sum_{\sigma \in S_{r}} c_{\sigma} \delta_{k_{\tau\sigma(1)}}^{k_{1}} \delta_{k_{\tau\sigma(2)}}^{k_{2}} \dots \delta_{k_{\tau\sigma(r)}}^{k_{r}} = \sum_{\sigma \in S_{r}} c_{\sigma} \delta_{\tau\sigma(1)}^{1} \delta_{\tau\sigma(2)}^{2} \dots \delta_{\tau\sigma(r)}^{r} \\ &= \sum_{\sigma \in S_{r}} c_{\sigma} \delta_{\tau(1)}^{\sigma^{-1}(1)} \delta_{\tau(2)}^{\sigma^{-1}(2)} \dots \delta_{\tau(r)}^{\sigma^{-1}(r)} = c_{\tau^{-1}}. \end{split}$$

If k_1, k_2, \dots, k_r are *not* mutually different, then

$$U^{k_{1}k_{2}...k_{r}}_{\kappa_{\tau(1)}k_{\tau(2)}...k_{\tau(r)}} = \sum_{\sigma \in S_{r}} c_{\sigma} \Delta_{\sigma}^{k_{1}k_{2}...k_{r}}_{\kappa_{\tau(1)}k_{\tau(2)}...k_{\tau(r)}}$$

$$= \sum_{\sigma \in S_{r}} c_{\sigma} \delta_{k_{\tau\sigma(1)}}^{k_{1}} \delta_{k_{\tau\sigma(2)}}^{k_{2}} ... \delta_{k_{\tau\sigma(r)}}^{k_{r}} = \sum_{\sigma \in S_{r}} c_{\sigma} \delta_{k_{\tau(1)}}^{k_{\sigma^{-1}(2)}} \delta_{k_{\tau(2)}}^{k_{\sigma^{-1}(2)}} ... \delta_{k_{\tau(r)}}^{k_{\sigma^{-1}(r)}}$$

$$= c_{\sigma_{1}} + c_{\sigma_{2}} + ... + c_{\sigma_{N}},$$

where $\sigma_1, \sigma_2, ..., \sigma_N$ are elements of the stabilizer of the *r*-tuple $k_1, k_2, ..., k_r$.

In particular, this number does not depend on τ . Note that equations $c_{\sigma} = c_{\sigma^{-1}}$ are symmetry conditions for the matrix $U^{l_1 l_2 \dots l_r}_{k_1 k_2 \dots k_r}$:

$$\begin{split} U^{l_l l_2 \dots l_r}_{k_l k_2 \dots k_r} &= \sum_{\sigma \in S_r} c_\sigma \Delta_{\sigma}^{l_l l_2 \dots l_r}_{k_l k_2 \dots k_r} = \sum_{\sigma \in S_r} c_{\sigma^{-1}} \Delta_{\sigma^{-1} \ k_l k_2 \dots k_r}^{l_l l_2 \dots l_r} \\ &= \sum_{\sigma \in S_r} c_{\sigma^{-1}} \Delta_{\sigma}^{k_l k_2 \dots k_r}_{l_l l_2 \dots l_r} \,. \end{split}$$

System (7) splits in two autonomous subsystems:

Lemma 5 Let $U \in T_r^r \mathbf{R}^n$, $U = U^{k_1 k_2 \dots k_r}_{l_1 l_2 \dots l_r}$, be a tensor. The following two conditions are equivalent:

(a) U is an invariant tensor. (b) The components $U^{k_1k_2...k_r}_{l_1l_2...l_r}$, such that $k_1, k_2, ..., k_r$ is not a permutation of $l_1, l_2, ..., l_r$, satisfy

(11)
$$U^{k_1k_2...k_r}_{l_1l_2...l_r} = 0,$$

and, if the superscripts are permutations of the subscripts, then

(12)
$$\sum_{\tau \in S_r} \delta_{i_{\tau(1)}}^{i_{\tau(1)}} \delta_{i_{\nu(2)}}^{i_{\tau(2)}} \dots \delta_{i_{\nu(r)}}^{i_{\tau(r)}} U^{l_{\mu(1)}l_{\mu(2)} \dots l_{\mu(r)}} {}_{l_{\tau(1)}l_{\tau(2)} \dots l_{\tau(r)}} \\ = \sum_{\tau \in S_r} \delta_{l_{\tau(1)}}^{l_{\mu(1)}} \delta_{l_{\tau(2)}}^{l_{\mu(2)}} \dots \delta_{l_{\tau(r)}}^{l_{\mu(r)}} U^{i_{\tau(1)}i_{\tau(2)} \dots i_{\tau(r)}} {}_{i_{\nu(1)}i_{\nu(2)} \dots i_{\nu(r)}}.$$

Proof 1. Suppose that $k_1, k_2, ..., k_r$ is not a permutation of $l_1, l_2, ..., l_r$. Consider equation (7) determined by the choice $j_p = i_p = l_p$. Since the left-hand side becomes $N(l_1l_2...l_r)U^{k_1k_2...k_r}_{l_{\tau(1)}l_{\tau(2)}...l_{\tau(r)}}$, where $N(l_1l_2...l_r)$ is the dimension of the stabilizer of the *r*-tuple $l_1, l_2, ..., l_r$, and the right-hand side vanishes, we get (11).

2. Subsystem of (7), satisfying condition (b), is exactly the system (12).

In equations (12) the subscripts and superscripts run through the index set 1,2,...,n, and $\mu,\nu \in S_r$ are arbitrary permutations; thus, we have $(r!)^2 n^{2r}$ equations for $r!n^r$ unknowns the components $U^{l_1l_2..l_r}_{l_{k(1)}l_{k(2)}..l_{k(r)}}$. Finally, note the following property of invariant tensors, arising from

Finally, note the following property of invariant tensors, arising from invariance with respect to suitable one-parameter subgroups of the general linear group.

Lemma 6 Let $U \in T_r^r \mathbf{R}^n$, $U = U^{k_1k_2...k_r}_{l_1l_2...l_r}$, be an invariant tensor. Then for all indices p,q and $k_1,k_2,...,k_r$, $l_1,l_2,...,l_r$, the components $U^{k_1k_2...k_r}_{l_1l_2...l_r}$, satisfy

$$\begin{split} \delta_{p}^{k_{1}}U^{qk_{2}k_{3}\ldots k_{r}} &+ \delta_{p}^{k_{2}}U^{k_{1}qk_{3}k_{4}\ldots k_{r}}{}_{j_{1}j_{2}\ldots j_{r}} + \ldots + \delta_{p}^{k_{r}}U^{k_{1}k_{2}\ldots k_{r-1}q}{}_{j_{1}j_{2}\ldots j_{r}} \\ &= \delta_{j_{1}}^{q}U^{k_{1}k_{2}\ldots k_{r}}{}_{pj_{2}j_{3}\ldots j_{r}} + \delta_{j_{2}}^{q}U^{k_{1}k_{2}\ldots k_{r}}{}_{j_{1}pj_{3}j_{4}\ldots j_{r}} + \ldots + \delta_{j_{r}}^{q}U^{k_{1}k_{2}\ldots k_{r}}{}_{j_{1}j_{2}\ldots j_{r-1}p}. \end{split}$$

Proof Consider equations of invariant tensors (6). Differentiating the left-hand side with respect to A_q^p at $A_q^p = \delta_q^p$ yields

$$\begin{split} &\delta_{p}^{k_{1}}\delta_{l_{1}}^{q}\delta_{l_{2}}^{k_{2}}\delta_{l_{3}}^{k_{3}}\dots\delta_{l_{r}}^{k_{r}}U^{l_{l}l_{2}l_{3}\dots l_{r}}{}_{j_{1}j_{2}\dots j_{r}}+\delta_{l_{1}}^{k_{1}}\delta_{p}^{k_{2}}\delta_{l_{2}}^{q}\delta_{l_{3}}^{k_{3}}\dots\delta_{l_{r}}^{k_{r}}U^{l_{l}l_{2}l_{3}\dots l_{r}}{}_{j_{1}j_{2}\dots j_{r}} \\ &+\dots+\delta_{l_{1}}^{k_{1}}\delta_{l_{2}}^{k_{2}}\dots\delta_{l_{r-1}}^{k_{r-1}}\delta_{p}^{k_{r}}\delta_{i_{r}}^{q}U^{l_{1}l_{2}\dots l_{r-1}l_{r}}{}_{j_{1}j_{2}\dots j_{r}}{}_{j_{1}j_{2}\dots j_{r}} \\ &=\delta_{p}^{k_{1}}U^{qk_{2}k_{3}\dots k_{r}}{}_{j_{1}j_{2}\dots j_{r}}+\delta_{p}^{k_{2}}U^{k_{1}qk_{3}k_{4}\dots k_{r}}{}_{j_{1}j_{2}\dots j_{r}}+\dots+\delta_{p}^{k_{r}}U^{k_{1}k_{2}\dots k_{r-1}q}{}_{j_{1}j_{2}\dots j_{r}}, \end{split}$$

and similarly for the right-hand side

$$\begin{split} &\delta_{p}^{l_{1}}\delta_{j_{1}}^{q}\delta_{j_{2}}^{l_{2}}\delta_{j_{3}}^{l_{3}}\dots\delta_{j_{r}}^{l_{r}}U^{k_{1}k_{2}\dotsk_{r}}{}_{l_{l}l_{2}\dots l_{r}}+\delta_{j_{1}}^{l_{1}}\delta_{p}^{l_{2}}\delta_{j_{2}}^{q}\delta_{j_{3}}^{l_{3}}\delta_{j_{4}}^{l_{4}}\dots\delta_{j_{r}}^{l_{r}}U^{k_{1}k_{2}\dotsk_{r}}{}_{l_{l}l_{2}\dots l_{r}} \\ &+\dots+\delta_{j_{1}}^{l_{1}}\delta_{j_{2}}^{l_{2}}\dots\delta_{j_{r-1}}^{l_{r-1}}\delta_{p}^{l_{r}}\delta_{j_{r}}^{q}U^{k_{1}k_{2}\dotsk_{r}}{}_{l_{1}l_{2}\dots l_{r}} \\ &=\delta_{j_{1}}^{q}U^{k_{1}k_{2}\dotsk_{r}}{}_{pj_{2}j_{3}\dots j_{r}}+\delta_{j_{2}}^{q}U^{k_{1}k_{2}\dotsk_{r}}{}_{l_{1}pj_{3}j_{4}\dots j_{r}}+\dots+\delta_{j_{r}}^{q}U^{k_{1}k_{2}\dotsk_{r}}{}_{j_{1}j_{2}\dots j_{r-1}p}. \end{split}$$

Now we are in a position to state and prove the fundamental theorem on the structure of invariant tensors. The proof is based on the trace decomposition theory, particularized to invariant tensors.

Theorem (Gurevich) Let $U \in T_s^r \mathbf{R}^n$, $U = U^{k_1 k_2 \dots k_r}_{l_1 l_2 \dots l_r}$, be a tensor. (a) If $r \neq s$, then U is invariant if and only if

U = 0.

(b) Suppose that r = s. Then U is invariant if and only if there exist numbers $a_{\sigma} \in \mathbf{R}$, where $\sigma \in S_r$, such that

(13)
$$U = \sum_{\sigma \in S_r} a_{\sigma} \Delta_{\sigma}.$$

Proof Assertion (a), and also sufficiency of condition (13), have already been proved (Lemma 1, Lemma 3). Thus, only necessity of condition (13) needs proof.

1. For any matrix $A \in GL_n(\mathbf{R})$, $A = A_j^i$, and any tensor $U \in T_r^r \mathbf{R}^n$, $U = U^{i_1 i_2 \dots i_r}_{j_1 j_2 \dots j_r}$, denote for short $\tilde{U} = \tilde{U}^{i_1 i_2 \dots i_r}_{j_1 j_2 \dots j_r}$, where

$$\tilde{U}^{i_{l_{2}\ldots i_{r}}}_{j_{1}j_{2}\ldots j_{r}} = A^{k_{1}}_{i_{1}}A^{k_{2}}_{i_{2}}\ldots A^{k_{r}}_{i_{r}}\tilde{A}^{j_{1}}_{l_{1}}\tilde{A}^{j_{2}}_{l_{2}}\ldots \tilde{A}^{j_{r}}_{l_{r}}U^{i_{1}j_{2}\ldots i_{r}}_{i_{1}j_{2}j_{2}\ldots j_{r}}.$$

It is easily seen that if $U^{i_1i_2...i_r}_{j_1j_2...j_r}$ is $\delta^{(p)}$ -generated, then also the tensor $\tilde{U}^{i_1i_2...i_r}_{j_1j_2...j_r}$ is $\delta^{(p)}$ -generated. Consider a $\delta^{(p)}$ -generated tensor U of the form

$$U^{i_{1}i_{2}...i_{r}} = \sum_{\kappa,\lambda \in S_{r}} \delta^{i_{\lambda(1)}}_{j_{\kappa(1)}} \delta^{i_{\lambda(2)}}_{j_{\kappa(2)}} ... \delta^{i_{\lambda(p)} \ \lambda(1),\lambda(2),...,\lambda(p)}_{j_{\kappa(p)} \ \kappa(1),\kappa(2),...,\kappa(p)} V^{i_{\lambda(p+1)}i_{\lambda(p+2)}...i_{\lambda(r)}}_{j_{\kappa(p+1)}j_{\kappa(p+2)}...j_{\kappa(r)}}$$

The component $\tilde{U}^{i_1i_2...i_r}_{j_1j_2...j_r}$ then includes a factor $A^{k_1}_{i_1}A^{k_2}_{i_2}...A^{k_r}_{i_r}\tilde{A}^{j_1}_{l_1}\tilde{A}^{j_2}_{l_2}...\tilde{A}^{j_r}_{l_r}$ and a factor

$$\begin{split} A_{i_{\lambda(1)}}^{k_{\lambda(1)}} A_{i_{\lambda(2)}}^{k_{\lambda(2)}} \dots A_{i_{\lambda(p)}}^{k_{\lambda(p)}} \tilde{A}_{l_{\kappa(1)}}^{j_{\kappa(1)}} \tilde{A}_{l_{\kappa(2)}}^{j_{\kappa(2)}} \dots \tilde{A}_{l_{\kappa(p)}}^{j_{\kappa(p)}} \delta_{j_{\kappa(1)}}^{i_{\lambda(1)}} \delta_{j_{\kappa(2)}}^{i_{\lambda(2)}} \dots \delta_{j_{\kappa(p)}}^{i_{\lambda(p)}} \\ &= A_{i_{\lambda(1)}}^{k_{\lambda(1)}} \tilde{A}_{l_{\kappa(1)}}^{j_{\kappa(1)}} \delta_{j_{\kappa(1)}}^{i_{\lambda(1)}} A_{i_{\lambda(2)}}^{k_{\lambda(2)}} \tilde{A}_{l_{\kappa(2)}}^{j_{\kappa(2)}} \delta_{j_{\kappa(2)}}^{i_{\lambda(2)}} \dots A_{i_{\lambda(p)}}^{k_{\lambda(p)}} \tilde{A}_{l_{\kappa(p)}}^{j_{\kappa(p)}} \delta_{j_{\kappa(p)}}^{i_{\lambda(p)}} \\ &= A_{s_{1}}^{k_{\lambda(1)}} \tilde{A}_{l_{\kappa(1)}}^{s_{1}} A_{s_{1}}^{k_{\lambda(2)}} \tilde{A}_{l_{\kappa(2)}}^{s_{1}} \dots A_{s_{p}}^{k_{\lambda(p)}} \tilde{A}_{l_{\kappa(p)}}^{s_{p}} \\ &= \delta_{l_{\kappa(1)}}^{k_{\lambda(1)}} \delta_{l_{\kappa(2)}}^{k_{\lambda(2)}} \dots \delta_{l_{\kappa(p)}}^{k_{\lambda(p)}}. \end{split}$$

Thus $\tilde{U}^{i_l i_2 \dots i_r}_{j_l j_2 \dots j_r}$ is $\delta^{(p)}$ -generated.

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2. Now let $U = U^{i_1i_2...i_r}_{j_1j_2...j_r}$ be an arbitrary *invariant* tensor. Consider the complete trace decomposition $U = {}^0U + {}^1U + {}^2U + ... + {}^rU$ (Lemma 2). Writing $\tilde{U}^{i_1i_2...i_r}_{j_1j_2...j_r} = A^{k_1}_{i_1}A^{k_2}_{i_2}...A^{k_r}_{i_r}\tilde{A}^{j_1}_{l_1}\tilde{A}^{j_2}_{l_2}...\tilde{A}^{j_r}_{l_r}U^{i_1i_2...i_r}_{l_r}$ as above, we have by hypothesis $U = \tilde{U}$ hence

$${}^{0}U + {}^{1}U + {}^{2}U + \ldots + {}^{r}U = {}^{0}\tilde{U} + {}^{1}\tilde{U} + {}^{2}\tilde{U} + \ldots + {}^{r}\tilde{U}.$$

Then, however, from Part 1 of this proof and Lemma 2, ${}^{p}U = {}^{p}\tilde{U}$ for all p. We wish to show that invariance of U implies

(14)
$${}^{0}U = 0, {}^{2}U = 0, {}^{2}U = 0, ..., {}^{r-1}U = 0.$$

First we show that ${}^{0}U = 0$. Consider equations of invariant tensors (7)

$$\begin{split} &\sum_{\tau \in S_r} \delta_{j_1}^{i_{\tau(1)}} \delta_{j_2}^{i_{\tau(2)}} \dots \delta_{j_r}^{i_{\tau(r)}} U^{k_1 k_2 \dots k_r} {}_{l_{\tau(1)} l_{\tau(2)} \dots l_{\tau(r)}} \\ &= \sum_{\tau \in S_r} \delta_{l_{\tau(1)}}^{k_1} \delta_{l_{\tau(2)}}^{k_2} \dots \delta_{l_{\tau(r)}}^{k_r} U^{i_{\tau(1)} l_{\tau(2)} \dots l_{\tau(r)}} {}_{j_1 j_2 \dots j_r} \end{split}$$

and apply this condition to the traceless tensor ${}^{0}U = W^{k_{1}k_{2}...k_{r}}_{l_{1}l_{2}...l_{r}}$. Then expression on the left-hand side can be viewed, for any fixed indices $i_1, i_2, \dots, i_r, j_1, j_2, \dots, j_r$ as a tensor indexed with superscripts k_1, k_2, \dots, k_r and subscripts l_1, l_2, \dots, l_r . But this tensor is both traceless and Kronecker, thus,

(15)
$$\sum_{\tau \in S_r} \delta_{j_1}^{i_{\tau(1)}} \delta_{j_2}^{i_{\tau(2)}} \dots \delta_{j_r}^{i_{\tau(r)}} W^{k_1 k_2 \dots k_r}_{l_{\tau(1)} l_{\tau(2)} \dots l_{\tau(r)}} = 0.$$

Clearly, this equation holds for all values of the indices. Restricting this system to a subsystem defined by the indices $i_p = j_p = l_p$, we have

$$\sum_{\tau \in S_r} \delta_{i_1}^{i_{\tau(1)}} \delta_{i_2}^{i_{\tau(2)}} \dots \delta_{i_r}^{i_{\tau(r)}} W^{k_1 k_2 \dots k_r}_{i_{\tau(1)} i_{\tau(2)} \dots i_{\tau(r)}} = 0.$$

Summation in this formula reduces to permutations $\tau \in S_r$ for which Summation in this formula reduces to permutations $\tau \in S_r$ for which $\delta_{i_{r(1)}}^{i_1} \delta_{i_{r(2)}}^{i_2} \dots \delta_{i_{r(r)}}^{i_r} = 1$, that is, to the stabilizer of the *r*-tuple i_1, i_2, \dots, i_r . Then, however, $N(i_1i_2 \dots i_r)W^{k_1k_2\dots k_r}_{i_1i_2\dots i_r} = 0$, where $N(i_1i_2 \dots i_r)$ is the dimension of the stabilizer, hence $W^{k_1k_2\dots k_r}_{i_1i_2\dots i_r} = 0$, that is, ${}^{0}U = 0$. The tensors ${}^{p}U$, where $p = 1, 2, \dots, r-1$, can be considered in the same way. Setting ${}^{p}U = W^{k_1k_2\dots k_r}_{i_1i_2\dots i_r}$ we get a tensor which is primitive and $\delta^{(p)}$ -generated, but also $\delta^{(r)}$ -generated. This is only possible when (15) holds, so we get $W^{k_1k_2\dots k_r}_{i_1i_2\dots i_r} = 0$, that is, ${}^{p}U = 0$. 3. Taking into account formulas (14), the complete trace decomposition formula for an invariant tensor $U = U^{i_1i_2\dots i_r}_{j_1j_2\dots j_r}$ yields

 $U = {}^{r}U.$

Consequently, U must be of the form (13).

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